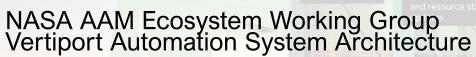
# High-Density Automated Vertiport Concept of Operations Overview



September 2<sup>nd</sup>, 2021

Departure from corridor "off-ramp"



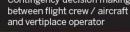






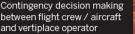


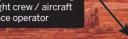
BOEING



assenger/Cargo

\_oading and Unloading Are









Communications, Navigation Surveillance and Information Eauipment monitors ncoming flights

Vertiport Operational

Key Aircraft trajectory Flight rerouted to another vertiport Surface navigation lines Charging cable Stakeholder function 3D surface trajectory Charging pads Staging pads

TLOF pads



GAMA

**Deloitte** 

#### Motivation

Develop a concept of operations to:

- Identify relevant requirements, considerations, barriers, and enabling technologies
- Inform operationalization of vertiports and maturation of vertiport automation technologies at UML-4

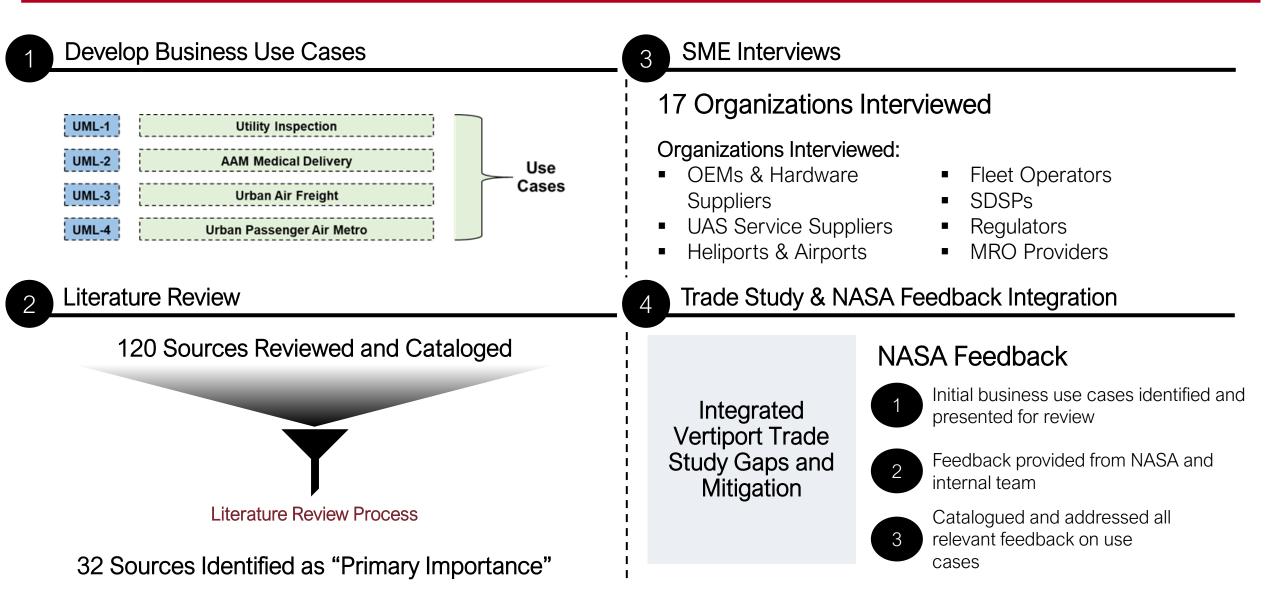








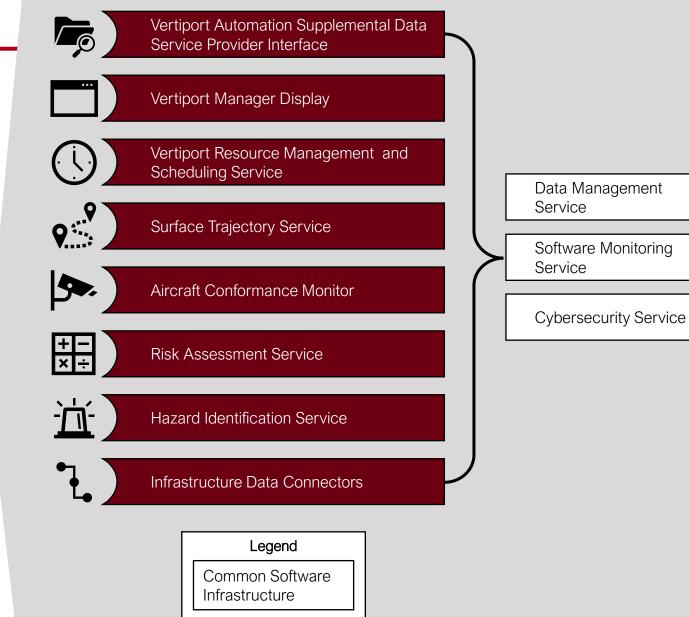
#### **Concept of Operations Development Process**





### Document Organization<sup>1</sup>

| 1. Introduction                   | Purpose and Scope                         |
|-----------------------------------|---|
|                                   | Assumptions and Constraints               |
|                                   | UML Mapping                               |
|                                   | Operational Stakeholder Descriptions      |
| 2. Current State                  | Description of Current State              |
|                                   | AAM Vertiport State-of-the-Art Assessment |
|                                   | Vertiport Challenges and Barriers         |
| 3. Desired Changes                | Rationale for Changes                     |
|                                   | Description of Desired Changes            |
|                                   | Description of the Proposed System        |
| 4. Future State                   | Operational Environment                   |
| Concept of<br>Operations          | Operational Stakeholders                  |
|                                   | Vertiport Automation System Services      |
|                                   | Vertiport Automation System Relationships |
|                                   | Configuration Decisions                   |
| 5. Operational<br>Scenarios       | Base Nominal Scenarios                    |
|                                   | Off-Nominal Scenarios                     |
|                                   | Resource Allocation                       |
| 6. Summary of Impacts             | Operational Impacts                       |
|                                   | Organizational Impacts                    |
|                                   | Impacts During Development                |
| 7. Analysis of<br>Proposed System | Summary of Improvements                   |
|                                   | Disadvantages and Limitations             |
|                                   | Alternatives and Tradeoffs Considered     |
|                                   | Path Forward                              |



Individual Service

### Vertiport Automation System

| VAS Services   | Service Role                 | Service Description  |
|--|------------------------------|--|
| Vertiport Resource Management<br>and Scheduling Service    | Core Function                | Responsible for determining vertiport configurations, implementing business rules, enforcing community and government-imposed requirements, and responding to resource requests to <b>strategically allocate and assign vertiport resources</b> .                      |
| Vertiport Automation Supplemental<br>Data Service Provider | External Interface           | <b>Standardized interface</b> allowing stakeholders to make <b>API calls</b> to the VAS and to use subscription as a means of direct communications to and from the VAS deployed at the vertiport.   |
| Surface Trajectory Service                                 | Support Function             | Determine taxiway and gate availability and <b>update a nominal or pre-planned 4D surface trajectory</b> (latitude, longitude, height above vertiport surface, and time) for aircraft surface movement.  |
| Vertiport Manager Display                                  | Support Function             | <b>Physical user interface</b> (UI) that describes the current state of vertiport operations and provides sufficiently detailed information to <b>adjust business objectives and configuration settings</b> and help clear operational anomalies and hazards.          |
| Infrastructure Data Connectors                             | Support Function<br>/ Safety | <b>Connects vertiport infrastructure</b> , whether owned and operated by the vertiport or an SDSP, to VAS Services. Examples include Weather, Foreign Object Debris Detection, Surveillance, Charging, Noise, Communications, and Resource Service.                    |
| Aircraft Conformance Monitor                               | Safety                       | Monitors aircraft conformance on the vertiport surface and within the surrounding airspace for compliance with scheduled arrival and departure operations.   |
| Hazard Identification Service                              | Safety                       | Receives anomaly alerts from the Aircraft Conformance Monitor and Software Monitoring Service, detects anomalies using vertiport infrastructure sensors, <b>identifies hazards from those anomalies</b> , and sends identified hazards to the Risk Assessment Service. |
| Risk Assessment Service                                    | Safety                       | Supports the vertiport Safety Management System (SMS) program by automating parts of the Safety Risk Management process through <b>estimating pre-identified hazard risks</b> .  |
| Data Management System                                     | Common<br>Software           | Manages data across the VAS and serves as the central repository and database manager, ensuring that each service has access to the right data at the right time.  |
| Cybersecurity Service                                      | Common<br>Software           | Authenticates and validates data requests from external users, between VAS services, and monitors for anomalies in VAS services for indications of security breaches.  |
| Software Monitoring Service                                | Common<br>Software           | Ensures that each VAS service is behaving as expected and <b>provides an assessment of operational status</b> for each service.  |

#### Operational Viewpoint – 1 Diagram (Integrated View)

Vertiport Operations Area (VOA): Transparent Red Cylinder The VOA is a construct to ensure the safety of high-density flight operations around vertiports.

#### Vertiport Volume (VPV): Transparent White Cylinder

The VPV is tightly coupled with the vertiport's geographic location, and traffic cannot flow through the VPV unless the flight has been cleared by the vertiport manager.



This ConOps does not describe the airspace design. The AAM Managed Corridors are used to signify that there is a volume of airspace designated for AAM aircraft in which high-density traffic can approach and depart from vertiports.





The Vertiport Operational Control Center is used to indicate a "central" vertiport, managing several vertiports digitally connected in the geographic region.



PSU A

- Vertiport operations assume predetermined approach and departure fixes
- The Vertiport Operations Area (VOA) and Vertiport Volume (VPV) will be charted on aeronautical charts
- The PSU manages the airspace in the VOA and VPV
- Air traffic will be a mix of piloted, semi-automated, and fully automated aircraft
- Flight crews will be remote or onboard the aircraft
- Sufficient CNSI technology will be onboard the aircraft
- Vertiports may need to comply with local, state, or federal regulations
- The PSU is responsible to act as the broker of timing, routing, and sequencing of aircraft in AAM Corridors
- AAM aircraft will follow 4D required navigation performance (RNP) trajectories



| <ul> <li>Taxi and Takeoff</li> <li>1. PSU coordinates takeoff time slot with vertiport and aircraft is sequenced for taxi and takeoff</li> <li>2. Flight crew and aircraft taxi on vertiport generated 4D surface trajectories while self-separating</li> <li>3. Aircraft arrives at the departure pad, PSU performs airspace checks, and clears the aircraft for takeoff</li> </ul> | <ol> <li>Land, Taxi, and Deplane         <ol> <li>The aircraft and flight crew are responsible for navigating the approach while remaining clear of static or dynamic obstacles</li> <li>The aircraft lands, and inform stakeholders of arrival</li> <li>The vertiport generates a 4D surface trajectory to navigate to the appropriate surface destination</li> <li>The vertiport monitors for potential hazards that would impact surface movement and generates alerts if necessary</li> <li>Passengers or cargo is offloaded from the aircraft assisted by ground crew</li> </ol> </li> </ol> |
|--|---|
| Climb and Cruise         Pre-Flight         1. Initialize vertiport operations and begin sharing resource availability information         2. Fleet operator files a flight plan         3. PSU verifies and facilitates flight plan request for vertiport approval  | T Manager Display<br>iport Operational  |

munications, Navigation,

eillance, and Information

ipment monitors

ming flights

Key

**A** 

Aircraft trajectory

Charging cable

Stakeholder function

Charging pads

Staging pads

TLOF pads

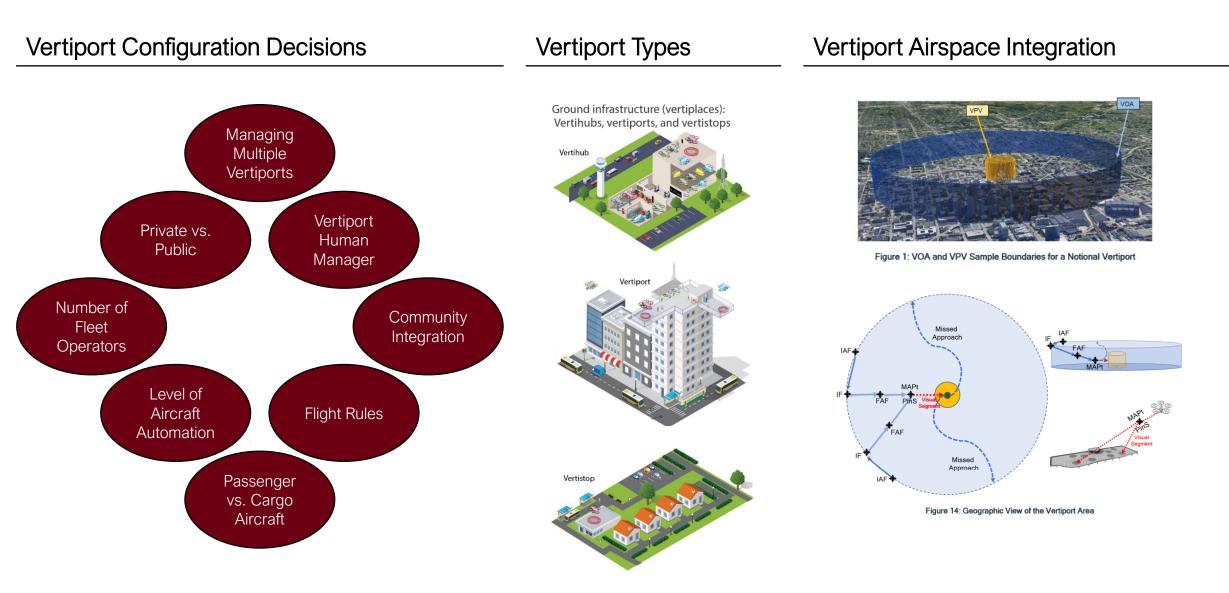
3D surface trajectory

Flight rerouted to another vertiport Surface navigation lines

9

- 4. Ground and flight crew aircraft, flight, and system
- 5. checkstiport provides resource availability information
- 5. Fleet operator authorizes and dispatches the flight

#### Vertiport Automation System Design Considerations





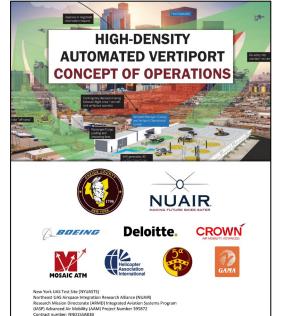
## Thank you







New York IJAS Tert Site (WTVIJATS) horthoast UJAS Alrapace integration Research Alliance (NUAIR) Research Mission Directorate (ARMD) Integrated Aviation Systems Program (UASP) Advanced Air Mobility (AAD) Project Number 395872 Contract number: NND155A838 July 26 2021



July 26 2021



Program (IASP) Advanced Air Mobility (AAM) Project Number 395872

Contract Number: NND155A83B July 26 2021



New York UAS Test Site (NYUASTS) Northast UAS Alispace Integration Research Alliance (NUAIR) Research Mission Directorate (ARRMD) Integrated Aviation Systems Program (UASP) Advanced air Medbilly (AdAM) Project Number 395872 Contract number: NND155A838 July 26 2021







11